

Hutchinson's Estimator is bad at Kronecker Trace Estimation

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Matrix-Vector Complexity

Many matvec-optimal algorithms proven recently

Great for applications where matvecs are:

- ① Efficiently Computable
- ② Computational Bottleneck

E.g. $\underline{x} \rightarrow f(A)\underline{x}$ via Lanczos Iteration

But what if ① does not hold?

We can only compute $A\underline{x}$ for some \underline{x} !

Kronecker Product

Let $A \in \mathbb{R}^{m \times n}$, $B \in \mathbb{R}^{p \times q}$. Then $A \otimes B \in \mathbb{R}^{mp \times nq}$

$$A \otimes B := \begin{bmatrix} [A]_{11}B & [A]_{12}B & \dots & [A]_{1m}B \\ [A]_{21}B & [A]_{22}B & \dots & [A]_{2m}B \\ \vdots & \vdots & \ddots & \vdots \\ [A]_{n1}B & [A]_{n2}B & \dots & [A]_{nm}B \end{bmatrix}$$

For vectors $\underline{x} \in \mathbb{R}^m$, $\underline{y} \in \mathbb{R}^p$, $\underline{x} \otimes \underline{y} \in \mathbb{R}^{mp}$

$$\underline{x} \otimes \underline{y} = \begin{bmatrix} x_1 \underline{y} \\ x_2 \underline{y} \\ \vdots \\ x_m \underline{y} \end{bmatrix}$$

vectors are underlined

Kronecker-Matrix-Vector Oracle Model

Before: $A \in \mathbb{R}^{d \times d}$. We can compute $A\underline{x}$ for any $\underline{x} \in \mathbb{R}^d$

Now: $A \in \mathbb{R}^{d^K \times d^K}$. We can compute $A\underline{x}$ for any $\underline{x} = \underline{x}_1 \otimes \underline{x}_2 \otimes \dots \otimes \underline{x}_K$
 $\underline{x}_1, \dots, \underline{x}_K \in \mathbb{R}^d$

Can we still solve linear algebra problems efficiently?

poly($d, K, \frac{1}{\epsilon}$)?

Core Issue: d^K vs dK parameters

Trace Estimation

Estimate $\text{tr}(A)$ from few matvecs

Find \tilde{t} such that

$$(1-\epsilon) \text{tr}(A) \leq \tilde{t} \leq (1+\epsilon) \text{tr}(A)$$

Classically,

Hutchinson's Estimator uses $\Theta(1/\epsilon^2)$ matvecs

Hutch++ uses $\Theta(1/\epsilon)$ matvecs \leftarrow Variance Reduction

Our Contribution: Analyze **Kronecker-Hutchinson**

Hutchinson's Estimator can easily be made Kronecker

How many matvecs are needed for $\text{std dev} \leq \epsilon \text{tr}(A)$?

Answer: $l = \Theta\left(\frac{3^k}{\epsilon^2}\right)$ are needed [Ahle et al. '20]

Further: Exact variance,

$O\left(\frac{2^k}{\epsilon^2}\right)$ for random rank-one matrices

$\Theta\left(\frac{2^k}{\epsilon^2}\right)$ needed for complex matvecs



The matrices where $\exp(K)$ matvecs are needed are either:

① Low Rank or ② $A = A_1 \otimes A_2 \otimes \dots \otimes A_k$

We can compute $\text{tr}(A)$ exactly efficiently in both cases 

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Hutchinson's Estimator

$$H_\ell(A) := \frac{1}{\ell} \sum_{i=1}^{\ell} \mathbf{g}_i^T A \mathbf{g}_i \quad \text{where} \quad \mathbf{g}_i \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

Let $\hat{A} = \frac{1}{2}(A + A^T)$ be the symmetrized A
 $= U \Lambda U^T$
↖ eigenvalues

$$\text{Then } \mathbf{g}^T A \mathbf{g} = \mathbf{g}^T \hat{A} \mathbf{g} \stackrel{\text{dist}}{=} \mathbf{g}^T \Lambda \mathbf{g} = \sum_i \lambda_i g_i^2$$

$$\text{So } \mathbb{E}[\mathbf{g}^T A \mathbf{g}] = \text{tr}(\hat{A}) \\ = \text{tr}(A)$$

$$\text{Var}[\mathbf{g}^T A \mathbf{g}] = 2 \|\hat{A}\|_F^2$$

$$\leq 2 \|A\|_F^2$$

$$\leq 2(\text{tr}(A))^2$$

for PSD A

Kronecker Hutchinson

Let $\underline{x} = \underline{x}_1 \otimes \dots \otimes \underline{x}_n$ for $\underline{x}_i \stackrel{iid}{\sim} \mathcal{N}(\underline{0}, \mathbf{I})$
Sample $\underline{x}^T \mathbf{A} \underline{x}$

What is $\mathbb{E}[\underline{x}^T \mathbf{A} \underline{x}]$? $\text{Var}[\underline{x}^T \mathbf{A} \underline{x}]$?

Problem: \underline{x} is not rotationally invariant!

Solution: "Extract" one \underline{x}_i at a time

Extraction

$$\mathbf{x} \otimes \mathbf{y} = (\mathbf{I}_n \otimes \mathbf{y})\mathbf{x} = (\mathbf{x} \otimes \mathbf{I}_m)\mathbf{y}$$

$K=2$

$$\begin{aligned} & (\underline{x}_1 \otimes \underline{x}_2)^T A (\underline{x}_1 \otimes \underline{x}_2) \\ \underline{x}_1^T & \underbrace{(\underline{x}_1 \otimes \underline{x}_2)^T A (\mathbf{I} \otimes \underline{x}_2)}_{\underline{x}_1^T M \underline{x}_1} \underline{x}_1 \end{aligned}$$

$$E_{\underline{x}_1}[\underline{x}^T A \underline{x}] = \text{tr}(M) = \underline{x}_2^T \text{tr}_1(A) \underline{x}_2 \quad \text{Partial Trace of } A$$

$$\text{Var}_{\underline{x}_1}[\underline{x}^T A \underline{x}] = 2 \|\frac{1}{2}(M + M^T)\|_F^2 \quad \text{Partially Symmetrize } A$$

Core Theorem

Let $\bar{A} = \frac{1}{2^K} \sum_{\nu \subseteq \{1, \dots, K\}} A^{\top \nu}$ be the average of all partial symmetrizations of A .

$$\begin{aligned} \text{Then } \text{Var}[x^T A x] &= \sum_{S \subseteq \{1, \dots, K\}} 2^{K-|S|} \|\text{tr}_S(A)\|_F^2 \\ &\leq \sum_{S \subseteq \{1, \dots, K\}} 2^{K-|S|} \|\text{tr}_S(A)\|_F^2 \\ &\leq 3^K (\text{tr}(A))^2 \quad \text{for PSD } A \end{aligned}$$

Proof: Lots of induction

Conclusions

- Introduce Kron-Mat-Vec Complexity
- Variance of Kron-Hutchinson Algo
- Surprising connection to Partial Trace, Partial Transpose
- $\Omega\left(\frac{3^K}{\epsilon^2}\right)$ lower bound when A is the all-ones matrix
- $\Omega\left(\frac{\sqrt{K}}{\epsilon^2}\right)$ lower bound against all Kron-Mat-Vec Algos

Double-Sparse Model

Suppose $A \in \mathbb{R}^{d \times d}$ on hard drive, but d is huge
You cannot store $\underline{x} \in \mathbb{R}^d$ in memory (RAM)

But cols of A are c -sparse E.g. banded matrices

If \underline{x} is s -sparse, then $A\underline{x}$ is cs -sparse

Allow $O(d)$ time but $o(d)$ memory
[Jonathan Weare, Robert Webber]